Providing the same advanced, multiplatform capabilities as APM 2.5, the 2.6 revision of the award-winning APM autopilot is designed for an external magnetometer. This improves flight performance by allowing the compass module (or combined GPS with compass) to be placed further away from sources of potential magnetic interference.

We recommend:
3DR GPS uBlox with Compass
Featuring active circuitry for ceramic patch antenna, rechargeable backup battery for warm starts, I2C EEPROM for configuration storage, and a digital compass. Available from Store.3DRobotics.com

PLANE
To set up your APM 2.6 board using the APM:Plane firmware please visit: PLANEARDUPILOT.COM

COPTER
To set up your APM 2.6 board using the APM:Copter firmware, please visit: COPTERARDUPILOT.COM

ROVER
To set up your APM 2.6 board using the APM:Rover firmware, please visit: ROVERARDUPILOT.COM

APM 2.6
FOR EXTERNAL MAGNETOMETER

APM 2.6 requires an external compass.